



Can Bus Operation

There is a new feature in the Vbox software. As there are more and more messages being sent over the CAN bus, there is the possibility that the VBox will not be able to process the messages fast enough.

To improve this, there are now two methods of operation.

Open

In this mode the VBox will only transmit data (eg latitude , velocity) over the CAN bus and will not communicate with any Racelogic modules.

The default CAN identifiers will be used.

e.g ID 301 for Sats in view , Time , Latitude.

Please see 'VBOX2PRO4_CAN_format.pdf' which can be found in your 'Racelogic\VBox\Documents\Application Notes\' directory.

Closed

This is designed to be a closed connection between the VBox and other Racelogic modules. There is to be no connection to an external CAN bus.

Only in this mode will you be able to enter the module set-up by pressing the 'Configure CAN & modules'.

